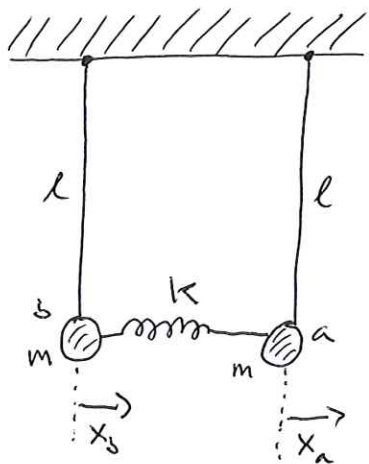


Coupled Oscillators [King Ch. 4]

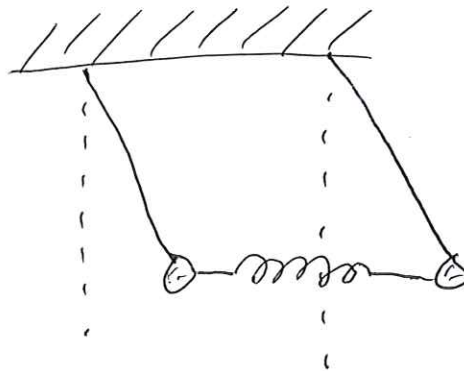
- Single (isolated) harmonic oscillators have only one way of oscillating, and they do so at their natural frequency ω_0
- Multiple oscillators that are coupled together (meaning energy can be exchanged b/t each osc.) collectively exhibit multiple frequencies of oscillation.
 - each frequency relates to a different way the coupled system can oscillate
 - These different ways are called "normal modes" and the associated frequencies are "normal frequencies"
- Normal modes characterized by the fact that all parts of the system oscillate at the same frequency (but not necessarily the same phase)
- Important to understand b/c harmonic oscillators rarely exist in isolation, & there are many examples of coupled oscillators
 - rattling car
 - vibrating atoms in crystals
 - ∞ coupled oscillators → continuous media & WAVES

Example: Consider two pendulums connected by a spring w/ spring constant k

9-2



• Case (A): Displace both masses by same amount in same direction

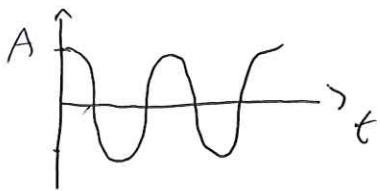
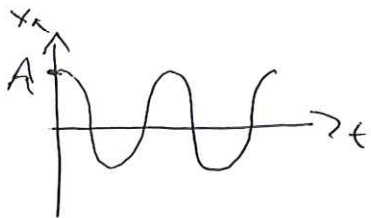


• spring remains unstretched & plays no role
pendulums ~~system~~ moves as if unconnected

$$x_a = A \cos \omega_1 t \quad x_b = A \cos \omega_1 t$$

$$\omega_1 = \sqrt{g/l}$$

($\phi_a = \phi_b = 0$ b/c start from rest)

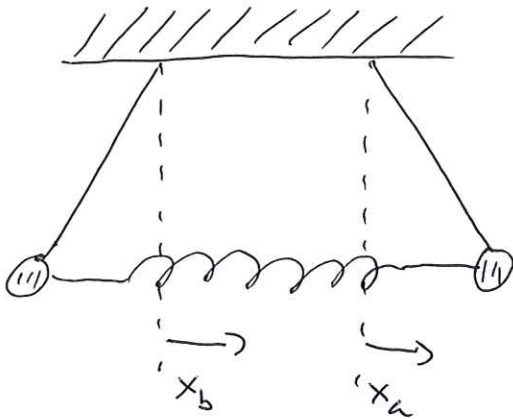


→ the masses oscillate in phase

"first normal mode of oscillation"

Case (B): Displace both masses by same amount
in opposite directions

9-3



• Spring gets stretched and compressed as pendulums swing

→ additional restoring force!

→ $x_a = -x_b$ due to mirror symmetry of setup

• Eq. of motion for mass a:

$$m \frac{d^2 x_a}{dt^2} = - \underbrace{\frac{mgx_a}{L}}_{\text{restoring force from gravity}} - \underbrace{2kx_a}_{\text{restoring force from spring}}$$

$$= -m\omega_2^2 x_a \quad \text{w/} \quad \omega_2 = \sqrt{\frac{g}{L} + \frac{2k}{m}}$$

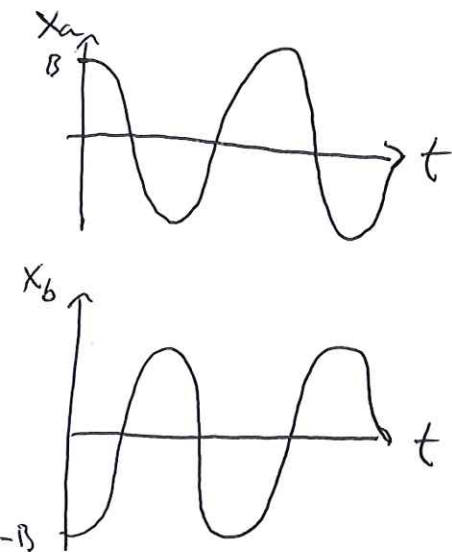
Solution: $x_a = B \cos \omega_2 t$

$$x_b = -x_a = -B \cos \omega_2 t$$

→ masses oscillate 180° out-of-phase

"2nd normal mode of oscillation"

$\omega_2 > \omega_1$ b/c has increased restoring force



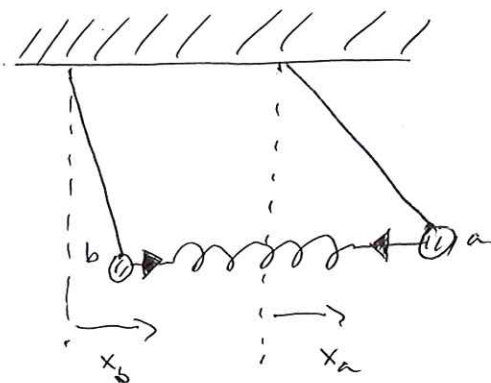
Summary of normal mode characteristics

9-41

- masses oscillate w/ same frequency
- masses perform simple harmonic motion w/ constant amplitude
- well-defined phase difference b/t masses: 0° or 180°
- if system gets excited in normal mode, it stays in that mode

Superposition of normal modes

- The above cases are special in that the motion was confined to a single normal mode: either $x_a = x_b$ or $x_a = -x_b$ at all times
- Generally, coupled oscillators can be in a superposition of the two normal modes



• Here, you can see that $x_a \neq \pm x_b$ at a given snapshot in time

• This gives spring extension $(x_a - x_b)$ that produces a force/tension $F = k(x_a - x_b)$

• Restoring force on mass a is then:

$$-\frac{mgx_a}{l} \quad \underbrace{-k(x_a - x_b)}_{\substack{\text{stretched spring gives force pushing} \\ \text{mass a toward EP}}}$$

• mass b:

$$-\frac{mgx_b}{l} \quad \underbrace{+k(x_a - x_b)}_{\substack{\text{stretched spring pulls} \\ \text{mass b away from EP}}}$$

\Rightarrow eqs. of motion:

9-5

$$\left. \begin{aligned} \text{[eq. 4.6]} \quad \frac{d^2 x_a}{dt^2} + \frac{g x_a}{l} + \frac{k}{m} (x_a - x_b) &= 0 \\ \text{[eq. 4.7]} \quad \frac{d^2 x_b}{dt^2} + \frac{g x_b}{l} - \frac{k}{m} (x_a - x_b) &= 0 \end{aligned} \right\} \begin{array}{l} x_a \text{ \& } x_b \text{ appear in} \\ \text{both eqs.} \end{array}$$

\rightarrow means they are coupled!

\rightarrow These eqs. cannot be solved separately, must be solved simultaneously

To do so, take the sum & difference:

$$\text{Sum: [4.6] + [4.7] : } \frac{d^2 (x_a + x_b)}{dt^2} + g \frac{(x_a + x_b)}{l} = 0$$

\rightarrow SHO w/ variable $(x_a + x_b)$ and freq $\omega_1 = \sqrt{g/l}$
1st normal mode!

$$\text{Difference: [4.6] - [4.7] : } \frac{d^2 (x_a - x_b)}{dt^2} + \left(\frac{g}{l} + \frac{2k}{m} \right) (x_a - x_b) = 0$$

\rightarrow SHO w/ variable $(x_a - x_b)$ & $\omega_2 = \sqrt{\frac{g}{l} + \frac{2k}{m}}$
2nd normal mode!

Now define new coordinates that decouple diff. eqs.

$$\boxed{q_1 = (x_a + x_b)} \text{ \& } \boxed{q_2 = (x_a - x_b)} \quad \text{"normal coordinates"}$$

\rightarrow these oscillate independently (ie, not coupled) w/ freq. ω_1 & ω_2 and
"normal frequencies"

$$\left[\frac{d^2 q_1}{dt^2} + \omega_1^2 q_1 = 0 \right], \left[\frac{d^2 q_2}{dt^2} + \omega_2^2 q_2 = 0 \right]$$

General solutions are:

9-6

$$\boxed{q_1 = C_1 \cos(\omega_1 t + \phi_1)}, \quad \boxed{q_2 = C_2 \cos(\omega_2 t + \phi_2)}$$

Special cases:

(A) $q_2 = 0 \rightarrow x_a = x_b$ at all times! $(x_a + x_b = 0)$

(B) $q_1 = 0 \rightarrow x_a = -x_b$ at all times! $(x_a + x_b = 0)$

\rightarrow So from the general case we recover our initial consideration

This means that the motion of masses can generally be expressed as a superposition of normal modes:

$$\left. \begin{aligned} x_a &= \frac{1}{2}(q_1 + q_2) \\ x_b &= \frac{1}{2}(q_1 - q_2) \end{aligned} \right\} \begin{aligned} &\text{Constants } C_1, C_2, \phi_1, \phi_2 \text{ determined} \\ &\text{by initial conditions (displacement and} \\ &\text{velocity)} \\ &\text{(if initially at rest, } \phi_1 = \phi_2 = 0) \end{aligned}$$

If two masses start from rest, then $\phi_1 = \phi_2 = 0$

// Energy

$$E = \underbrace{\frac{1}{2} m \left(\frac{dx_a}{dt} \right)^2 + \frac{1}{2} m \left(\frac{dx_b}{dt} \right)^2}_{KE} + \underbrace{\frac{1}{2} \frac{mg}{\ell} (x_a^2 + x_b^2)}_{PE \text{ pendulum}} + \underbrace{\frac{1}{2} k (x_a - x_b)^2}_{PE \text{ spring}}$$

in terms of q_1, q_2 :

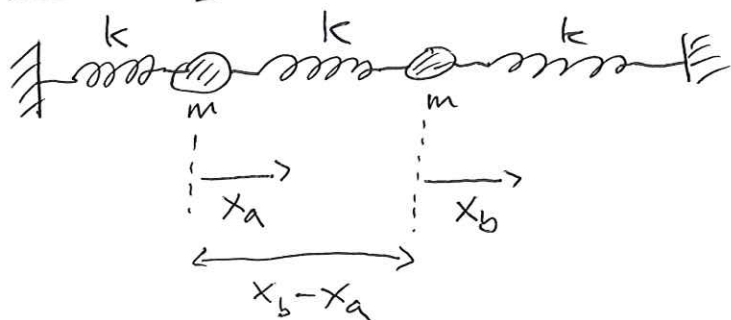
$$\rightarrow E = \left[\frac{1}{4} m \left(\frac{dq_1}{dt} \right)^2 + \frac{1}{4} \left(\frac{mg}{\ell} \right) q_1^2 \right] + \left[\frac{1}{4} m \left(\frac{dq_2}{dt} \right)^2 + \frac{1}{4} \left(\frac{mg}{\ell} + 2k \right) q_2^2 \right]$$

\rightarrow 2 independent oscillators

\rightarrow no energy flow b/t them

Oscillating masses coupled by springs

9-7



Consider forces for each mass:

Force arrows in displaced position

$$m \frac{d^2 x_a}{dt^2} = -kx_a + k(x_b - x_a) = kx_b - 2kx_a \quad [\text{eq. 4.18}]$$

$\hookrightarrow + k$ if $x_b - x_a > 0$, it creates force pulling x_a away from EP, not toward

$$m \frac{d^2 x_b}{dt^2} = -kx_b - k(x_b - x_a) = kx_a - 2kx_b \quad [\text{eq. 4.19}]$$

We are looking for normal mode solutions of form

$$x_a = A \cos \omega t, \quad x_b = B \cos \omega t$$

both masses oscillate at same frequency

Substituting x_a in eq. 4.18

$$-A m \omega^2 \cos \omega t = k B \cos \omega t - 2k A \cos \omega t$$

$$\text{gives } \rightarrow \frac{A}{B} = \frac{k}{(2k - m\omega^2)} \quad [4.20]$$

Substitute x_b in eq. 4.19

$$-B m \omega^2 \cos \omega t = k A \cos \omega t - 2k B \cos \omega t$$

$$\rightarrow \frac{A}{B} = \frac{(2k - m\omega^2)}{k}$$

Thus, $\frac{A}{B} = \frac{(2k - m\omega^2)}{k} = \frac{k}{(2k - m\omega^2)}$

9-8

$$\rightarrow (2k - m\omega^2)^2 = k^2$$

$$\rightarrow (2k - m\omega^2) = \pm k$$

$$\Rightarrow \omega^2 = \frac{k}{m} \quad \text{or} \quad \frac{3k}{m}$$

These are the two normal frequencies

Plug $\omega^2 = \frac{k}{m}$ into $\frac{A}{B} = \frac{k}{2k - m\omega^2}$ gives $A = B$

$\rightarrow 1^{st}$ normal mode, both masses oscillate in same direction

$$x_a = x_b = A \cos \omega_1 t \quad \omega_1 = \sqrt{\frac{k}{m}}$$

Plug $\omega^2 = \frac{3k}{m}$ in [4.20] gives $A = -B$

$$x_a = A \cos \omega_2 t \quad x_b = -A \cos \omega_2 t \quad \omega_2 = \sqrt{\frac{3k}{m}}$$

$\rightarrow 2^{nd}$ normal mode, masses oscillate in opposite directions

As before general solution is $x_a = \zeta_1 \cos \omega_1 t + \zeta_2 \cos \omega_2 t$

$$x_b = \zeta_1 \cos \omega_1 t - \zeta_2 \cos \omega_2 t$$

(include ϕ_1, ϕ_2 phases if initial velocity at $t=0$ is non zero)

Matrix Formalism for normal modes

9-9

• In our derivation above we had 2 eqs. to solve of form:

$$\begin{aligned} \frac{2k}{m} A - \frac{k}{m} B &= \omega^2 A \\ -\frac{k}{m} A + \frac{2k}{m} B &= \omega^2 B \end{aligned} \quad \Rightarrow \quad \text{matrix} \quad \begin{pmatrix} 2k/m & -k/m \\ -k/m & 2k/m \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} = \omega^2 \begin{pmatrix} A \\ B \end{pmatrix}$$

"eigenvalue problem" $\rightarrow \begin{pmatrix} 2k/m - \omega^2 & -k/m \\ -k/m & 2k/m - \omega^2 \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} = 0$

\nearrow
"eigen vector"

• Nonzero solutions if and only if determinant = 0

$$\rightarrow \left(\frac{2k}{m} - \omega^2 \right)^2 - \left(-\frac{k}{m} \right)^2 = 0 \quad \Rightarrow \quad \omega_1 = \sqrt{k/m} \quad \omega_2 = \sqrt{3k/m}$$

\rightarrow very useful if more than two oscillators involved

\rightarrow linear algebra, used a lot in quantum class

Outlook:

• Here, 2 masses coupled together moving in one dimension

\rightarrow 2 normal modes w/ coordinates q_1, q_2 and freq. ω_1, ω_2

• General: N masses connected, moving in 3D

$\rightarrow 3N$ normal modes with q_1, \dots, q_{3N} and

$\omega_1, \dots, \omega_{3N}$

Ex: Atoms in crystal are coupled

• if one atom vibrates, all atoms vibrate b/c coupled

• Crystal w/ N atoms has $3N$ normal modes!

\rightarrow Debye model for temp. dep. of heat capacity in crystals! (also need quantum harmonic osc.)

